

# Orthogonal polynomials of several discrete variables and the 3nj-Wigner symbols: applications to spin networks

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**Abstract.** The use of orthogonal polynomials for integral models on the lattice is applied to the 3nj-symbols that appear in the coupling of several angular momenta. These symbols are connected to the Ponzano-Regge method to solve the Einstein equations on a discrete Riemannian manifold.

## 1. Classical orthogonal polynomials of one discrete variable

These polynomials satisfy a difference equation of hypergeometric type such that the difference derivatives of the some polynomial satisfy a similar equation. The discrete variable can be consider of two types.

- a) *On homogeneous lattice:*  $x = 0, 1, 2, \dots$

The corresponding polynomials satisfy a difference equation

$$\sigma(x) \Delta \nabla p_n(x) + \tau(x) \Delta p_n(x) + \lambda_n p_n(x) = 0$$

with  $\Delta f(x) = f(x+1) - f(x)$ ,  $\nabla f(x) = f(x) - f(x-1)$ ,  $\sigma(x)$  and  $\tau(x)$  are functions of second and first order respectively;

an orthogonality relation

$$\sum_{x=a}^{b-1} p_n(x) p_m(x) \rho(x) = d_n^2 \delta_{mn}$$

with  $\rho(x)$  a weight function and  $d_n$  a normalization constant. To these polynomials correspond the Meixner, Kravchuk, Charlier and Hahn polynomials [1]

- b) *On non homogeneous lattice:*  $x = x(s)$ ,  $s = 0, 1, 2, \dots$  the polynomials satisfy a difference equation

$$\sigma[x(s)] \frac{\Delta}{\Delta x(s - \frac{1}{2})} \frac{\nabla y_n(x)}{\nabla x(s)} + \frac{1}{2} \tau[x(s)] \left\{ \frac{\Delta y_n(x)}{\Delta x(s)} + \frac{\nabla y_n(x)}{\nabla x(s)} \right\} + \lambda_n y_n(x) = 0;$$

an orthogonality relation

$$\sum_{s=a}^{b-1} y_n(s) y_m(s) \rho_n(x) \Delta x \left( s - \frac{1}{2} \right) = d_n^2 \delta_{nm}.$$

The corresponding polynomials are classified according to the lattice function:

For  $x(s) = s(s+1)$ , we have the Racah and dual Hahn polynomials

For  $x(s) = q^s$  or  $\frac{q^s - q^{-s}}{2}$ , we have the  $q$ -Kravchuk,  $q$ -Meixner,  $q$ -Charlier and  $q$ -Hahn polynomials.

For  $x(s) = \frac{q^s + q^{-s}}{2}$  or  $\frac{q^{is} + q^{-is}}{2}$ , we have the  $q$ -Racach and  $q$ -dual Hahn polynomials [2].

## 2. Generalized Clebsch-Gordon coefficients and generalized 3nj-Wigner symbols

If two angular momentum operators are coupled to give a total angular momentum  $J = J_1 + J_2$  the new basis can be expressed in terms of the old ones

$$|j_1 j_2 j m\rangle = \sum_{m_1 + m_2 = m} \langle j_1 j_2 m_1 m_2 | j_1 j_2 j m \rangle |j_1 j_2 m_1 m_2\rangle.$$

The symmetry properties of the Clebsch-Gordon coefficients in this expansion are more patent if one substitutes them by the Wigner symbols

$$\langle j_1 j_2 j m | j_1 j_2 m_1 m_2 \rangle = (-1)^{j_1 - j_2 + j - m} \sqrt{2j + 1} \begin{pmatrix} j_1 & j_2 & j \\ m_1 & m_2 & -m \end{pmatrix}$$

Similarly if we couple three angular momentum operator we obtain a new basis in terms of the old ones:

$$|j_1 j_2 j_3 j_{12} j m\rangle = \sum \langle j_1 j_2 j_3 m_1 m_2 m_3 | j_1 j_2 j_3 j_{12} j m \rangle |j_1 j_2 j_3 m_1 m_2 m_3\rangle$$

for the coupling  $(J_1 + J_2) + J_3 = J$ ,

$$|j_1 j_2 j_3 j_{23} j m\rangle = \sum \langle j_1 j_2 j_3 m_1 m_2 m_3 | j_1 j_2 j_3 j_{23} j m \rangle |j_1 j_2 j_3 m_1 m_2 m_3\rangle$$

for the coupling  $J_1 + (J_2 + J_3) = J$ .

Both bases are related by some matrix  $U(j_{12}, j_{23})$  that can be written in terms of generalized 6j-Wigner symbol

$$U(j_{12}, j_{23}) = (-1)^{j_1 + j_2 + j_3 + j} \sqrt{(2j_{12} + 1)(2j_{23} + 1)} \begin{Bmatrix} j_1 & j_2 & j_{12} \\ j_3 & j & j_{23} \end{Bmatrix}$$

In similar fashion can be written the generalized Clebsch-Gordon coefficients and generalized 3nj-Wigner symbols [3]. The algebraic properties of these symbols can be represented by geometrical graphs [3].

## 3. 3nj-symbols as orthogonal polynomials of several discrete variable

The 6j-symbols are proportional to the Racah polynomials through the following relation [2]

$$(-1)^{j_1 + j_2 + j_{23}} \sqrt{(2j_{12} + 1)(2j_{23} + 1)} \begin{Bmatrix} j_1 & j_2 & j_{12} \\ j_3 & j & j_{23} \end{Bmatrix} = \frac{\sqrt{\rho(x)}}{d_n} u_n^{(\alpha, \beta)}(x, a, b)$$

with

$$\begin{aligned} x(s) &= s(s+1), \quad s = j_{23} \\ a &= j_3 - j_2, \quad b = j + j_3 + 1, \quad n = j_{12} - j_1 + j_2 - j \\ \alpha &= j_1 - j_2 - j_3 + j, \quad \beta = j_1 - j_2 + j_3 - j \end{aligned}$$

Using the asymptotic limit of the Racah polynomials and the connections between the Jacobi polynomials and the Wigner little functions one can prove the following approximation of the 6j-symbols when  $j_1 \sim j_2 \sim j_3 \sim j \gg j_{12}$

$$\begin{Bmatrix} j_1 & j_2 & j_{12} \\ j_3 & j & j_{23} \end{Bmatrix} \simeq \frac{(-1)^{j_2 + j_3 + j_{23}}}{\sqrt{j_1 + j_2 + 1} \sqrt{j_3 + j + 1}} d_{j_1 - j_2, j_3 - j}^{j_{12}}(\vartheta) \quad (1)$$

with

$$\cos \theta = \frac{(2j_{23} + 1)^2 - (j_1 + j_2 + 1)^2 - (j_3 + j + 1)^2}{2(j_1 + j_2 + 1)(j_3 + j + 1)}$$

The  $3nj$ -symbols of the first and second kind can be written in terms of  $6j$ -symbols, and therefore in terms of product of Racah polynomials, giving rise to orthogonal polynomials of several discrete variables. To illustrate this take, f.i., the  $12j$ -symbol of the second kind as a combination of  $6j$ -symbols.

$$\begin{Bmatrix} j_1 & j_2 & j_3 & j_4 \\ l_1 & l_2 & l_3 & l_4 \\ k_1 & k_2 & k_3 & k_4 \end{Bmatrix} = \sum_x (2x + 1) (-1)^{R_n + 4x} \begin{Bmatrix} j_1 & k_1 & x \\ k_2 & j_2 & l_1 \end{Bmatrix} \begin{Bmatrix} j_2 & k_2 & x \\ k_3 & j_3 & l_2 \end{Bmatrix} \begin{Bmatrix} j_3 & k_3 & x \\ k_4 & j_4 & l_3 \end{Bmatrix} \begin{Bmatrix} j_4 & k_4 & x \\ k_1 & j_1 & l_4 \end{Bmatrix}$$

Here  $R_n = \sum_{i=1}^4 (j_i + l_i + k_i)$ . Substituting each  $6j$ -symbol for the corresponding Racah polynomial we obtain:

$$\begin{Bmatrix} j_1 & j_2 & j_3 & j_4 \\ l_1 & l_2 & l_3 & l_4 \\ k_1 & k_2 & k_3 & k_4 \end{Bmatrix} = \sum_x \frac{1}{2x + 1} \prod_{i=1}^4 \frac{\sqrt{\rho(l_i)}}{d_{n_i}} u_{n_i}^{(\alpha_i, \beta_i)}(l_i) \equiv p_n(l_1 l_2 l_3 l_4)$$

which is a polynomial of four discrete variables.

For the asymptotic limit we find

$$\begin{Bmatrix} j_1 & j_2 & j_3 & j_4 \\ l_1 & l_2 & l_3 & l_4 \\ k_1 & k_2 & k_3 & k_4 \end{Bmatrix} \approx \sum_x (2x + 1) \prod_{i=1}^4 \frac{1}{j_i + k_i + 1} d_{j_i - k_i, j_{i+1} - k_{i+1} (\bmod 4)}^x(\vartheta_i)$$

These formulas can be easily generalized to any  $3nj$ -symbols of first and second kind.

#### 4. Application to spin networks and to Ponzano-Regge integral action

Penrose has proposed a model for the space and time in which the underlying structure is given by a set of interactions between elementary units that satisfy the coupling of angular momentum operators, called spin networks [4]. One particular case of these networks can be described by the graphs of  $3nj$ -symbols. From different point of view Regge has proposed a method to calculate Einstein action by the approximation of curved riemannian manifold by a polyedron built up of triangles. Later Ponzano and Regge applied the properties of  $6j$ -symbols to calculate the sum action over this triangulation [5]

Let  $M$  be a riemannian manifold that is approximated by a polyedron with boundary  $D$  and it is decomposed into  $p$  tetrahedra  $T_k$  represented by  $6j$ -symbols.

The polyedron give rise to triangular faces  $f$ , represented by  $3j$ -symbols, and to  $q$  internal edges  $x_i$ , as well as to external ones  $l_i$  with respect to the boundary  $D$ .

Ponzano and Regge define the sum

$$S = \sum_{x_i} \prod_{k=1}^p T_k (-1)^\varphi \prod_{i=1}^q (2x_i + 1) \tag{2}$$

When  $l_i \rightarrow \infty$ ,  $\hbar \rightarrow 0$ ,  $\hbar l_i \rightarrow$  finite we recovered the continuous manifold. In order to compute the  $6j$ -symbols in te classical limit, we uses the assymptotic formula [2]

$$d_{mm'}^j(\theta) \approx (-1)^{m-m'} \sqrt{\frac{2}{\pi(j-m)}} \left( \frac{2j+m-m'+1}{2j-m+m'+1} \right)^{\frac{m+m'}{2}} \frac{\cos \left[ \left( j + \frac{1}{2} \right) \theta - \left( m - m' + \frac{1}{2} \right) \frac{\pi}{2} \right]}{\sqrt{\sin \theta}}$$

at  $m \sim m' \sim 1$ ,  $j \gg 1$ . Substituting this expression in (1) with  $m = j_1 - j_2$ ,  $m' = j_4 - j_5$ ,  $j = j_6$  and taking the edges of the tetrahedra  $j_1 + \frac{1}{2}, \dots, j_6 + \frac{1}{2}$ , very large except  $j_6$ , we have

$$\begin{aligned} \left\{ \begin{matrix} j_1 & j_2 & j_3 \\ j_4 & j_5 & j_6 \end{matrix} \right\} &\approx \frac{1}{\sqrt{12\pi V}} \cos \left\{ \left( j_6 + \frac{1}{2} \right) \theta - \left( j_1 + \frac{1}{2} \right) \frac{\pi}{2} + \right. \\ &\quad \left. + \left( j_2 + \frac{1}{2} \right) \frac{\pi}{2} - \left( j_4 + \frac{1}{2} \right) \frac{\pi}{2} + \left( j_5 + \frac{1}{2} \right) \frac{\pi}{2} + \frac{\pi}{4} \right\} = \\ &= \frac{1}{\sqrt{12\pi V}} \cos \left\{ \sum_{i=1}^6 \left( j_i + \frac{1}{2} \right) \theta_i + \frac{\pi}{4} \right\} \end{aligned} \quad (3)$$

where  $\theta_i$  is the dihedral angle for the edge  $j_i$  and  $V = \frac{1}{6} (j_1 + \frac{1}{2}) (j_4 + \frac{1}{2}) (j_6 + \frac{1}{2}) \sin \theta$ . Note the formula (3) has been proved rigorously by Roberts [5]. Introducing formula (3) in formula (2), Ponzano and Regge proved that it leads in the continuous limit to the integral action of the general relativity.

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